

What we mean by “cloud:”
The perils of
evaluating climate models
with satellite observations

Robert Pincus, University of Colorado

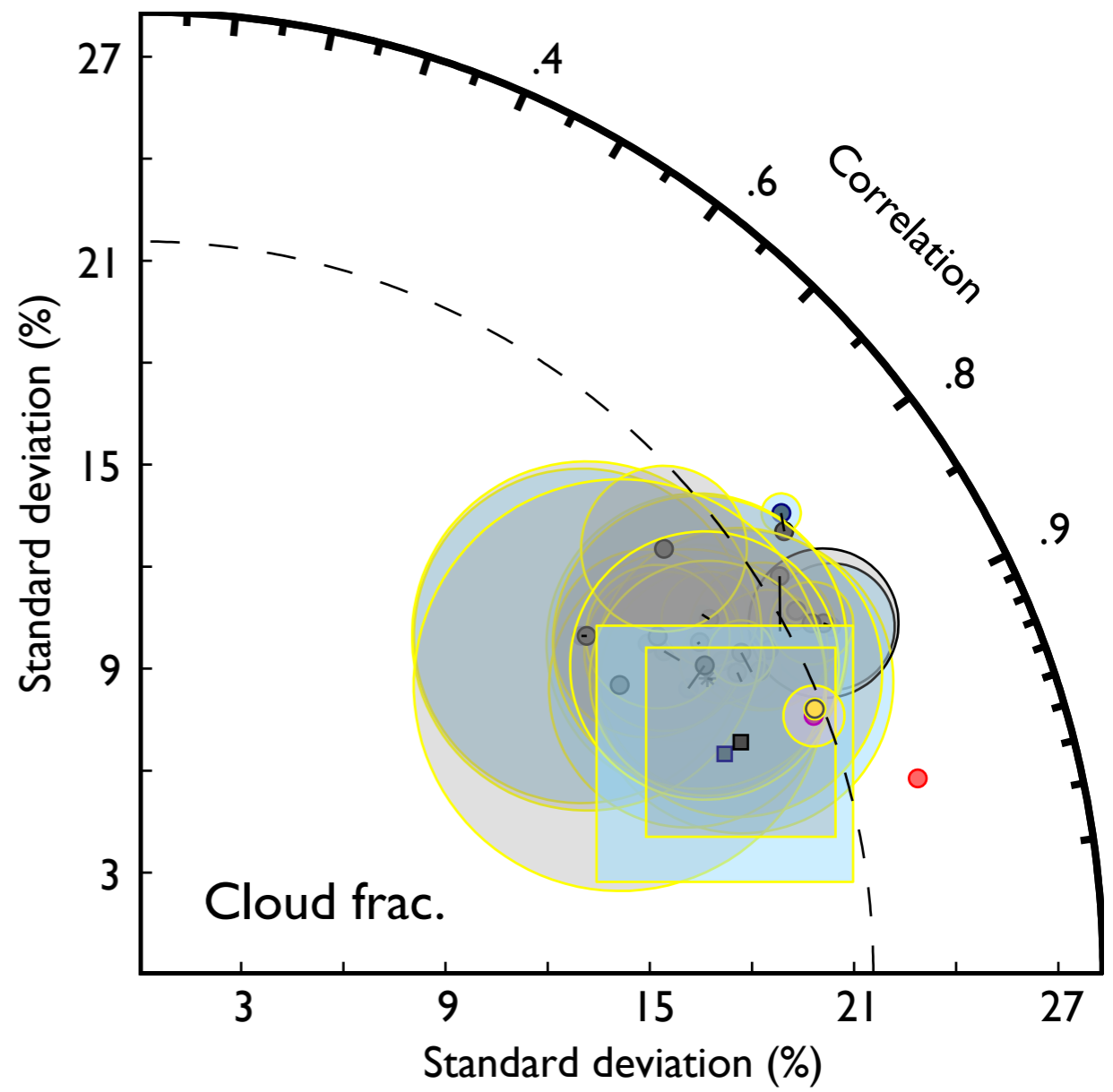
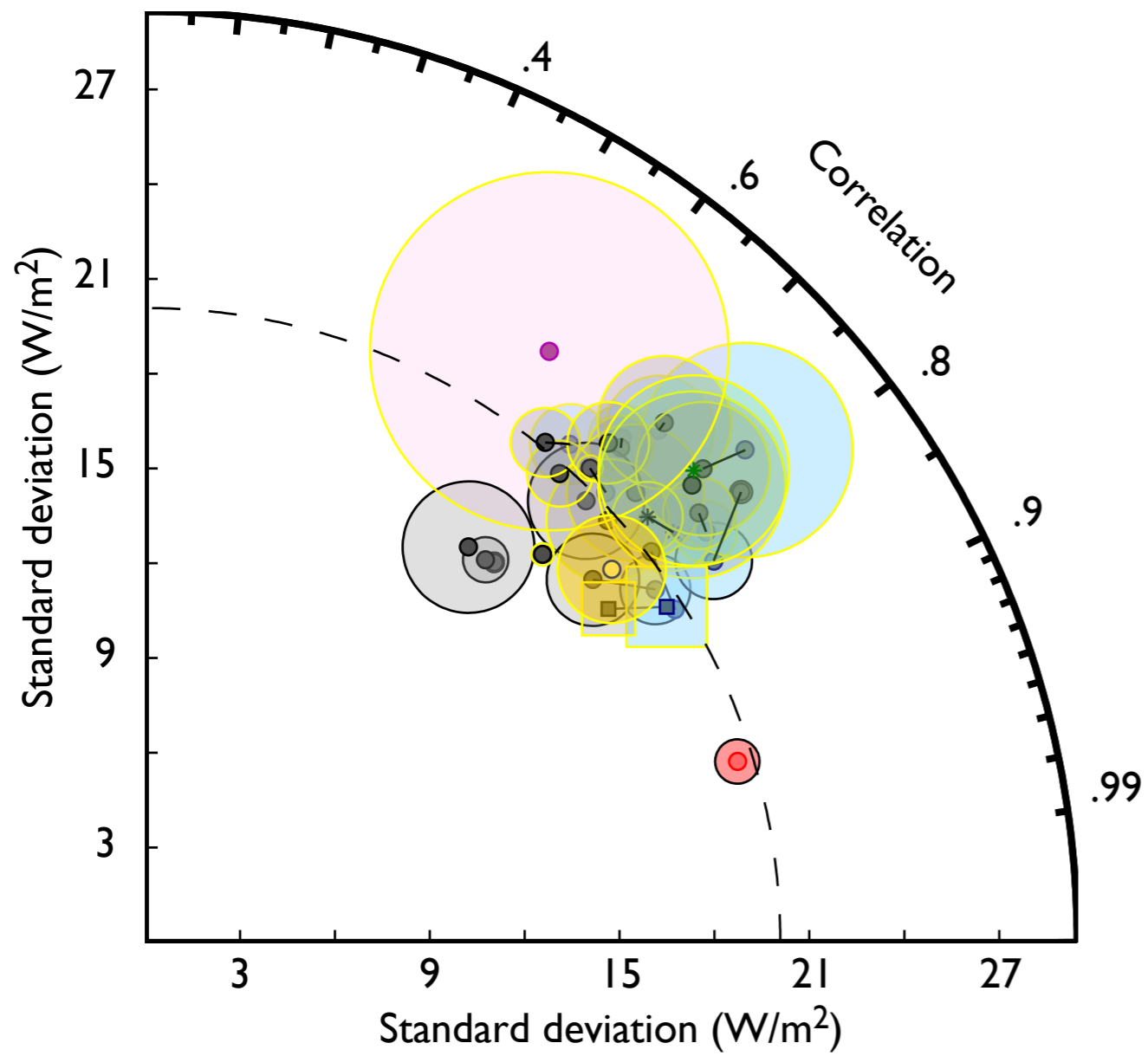
Steven Platnick, NASA/GSFC

Steve Ackerman, University of Wisconsin

Richard Hemler, NOAA/GFDL

R. J. Patrick Hofmann, University of Colorado

Based on Pincus et al, manuscript submitted to *J. Climate*



Making fair comparisons

We want to be able to attribute *differences* between observations and models to *model errors*

Some comparisons (e.g. temperature) can be direct, but satellites don't observe model cloud states

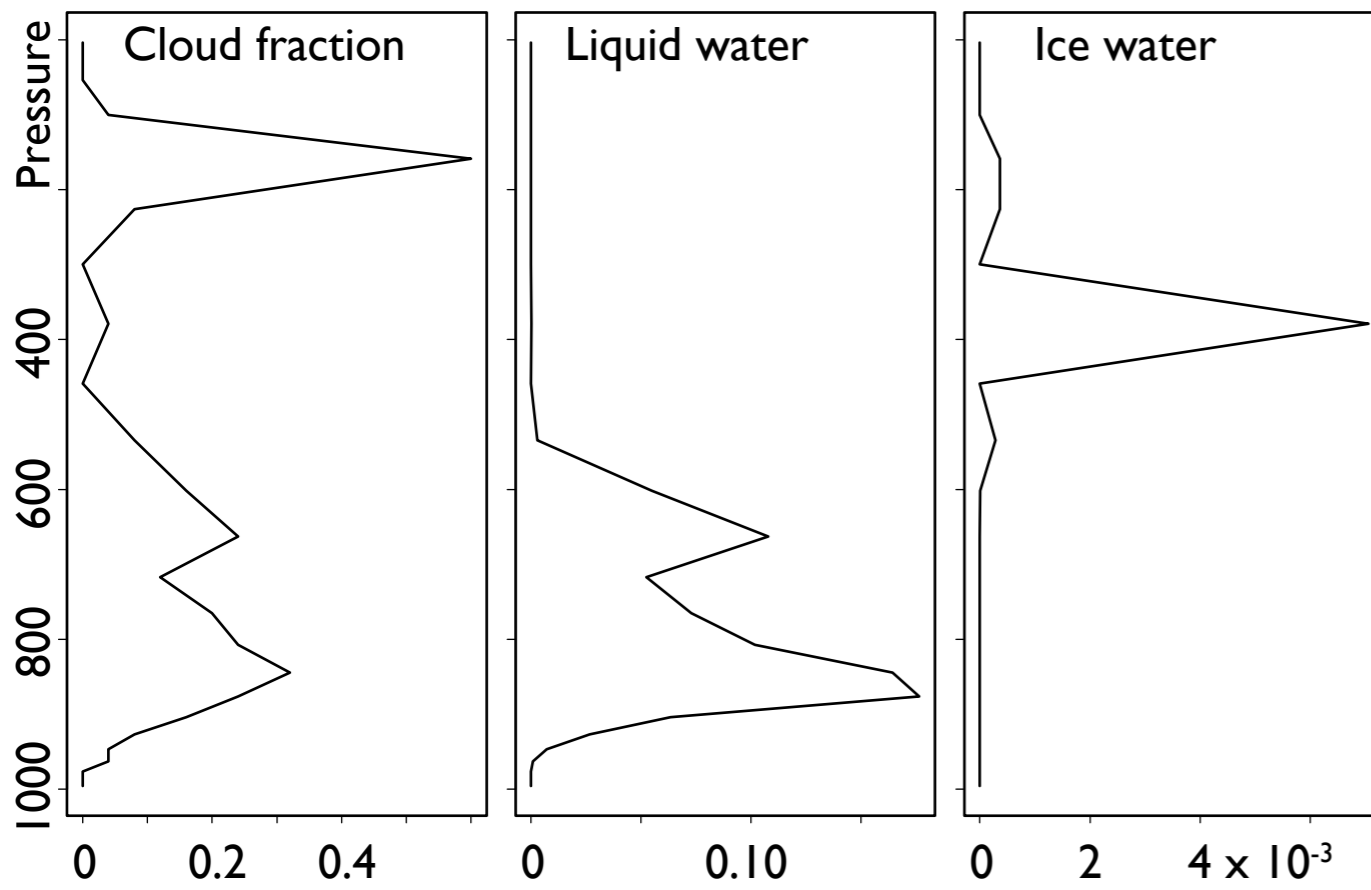
We require models of

- sub-grid scale distribution of cloudiness

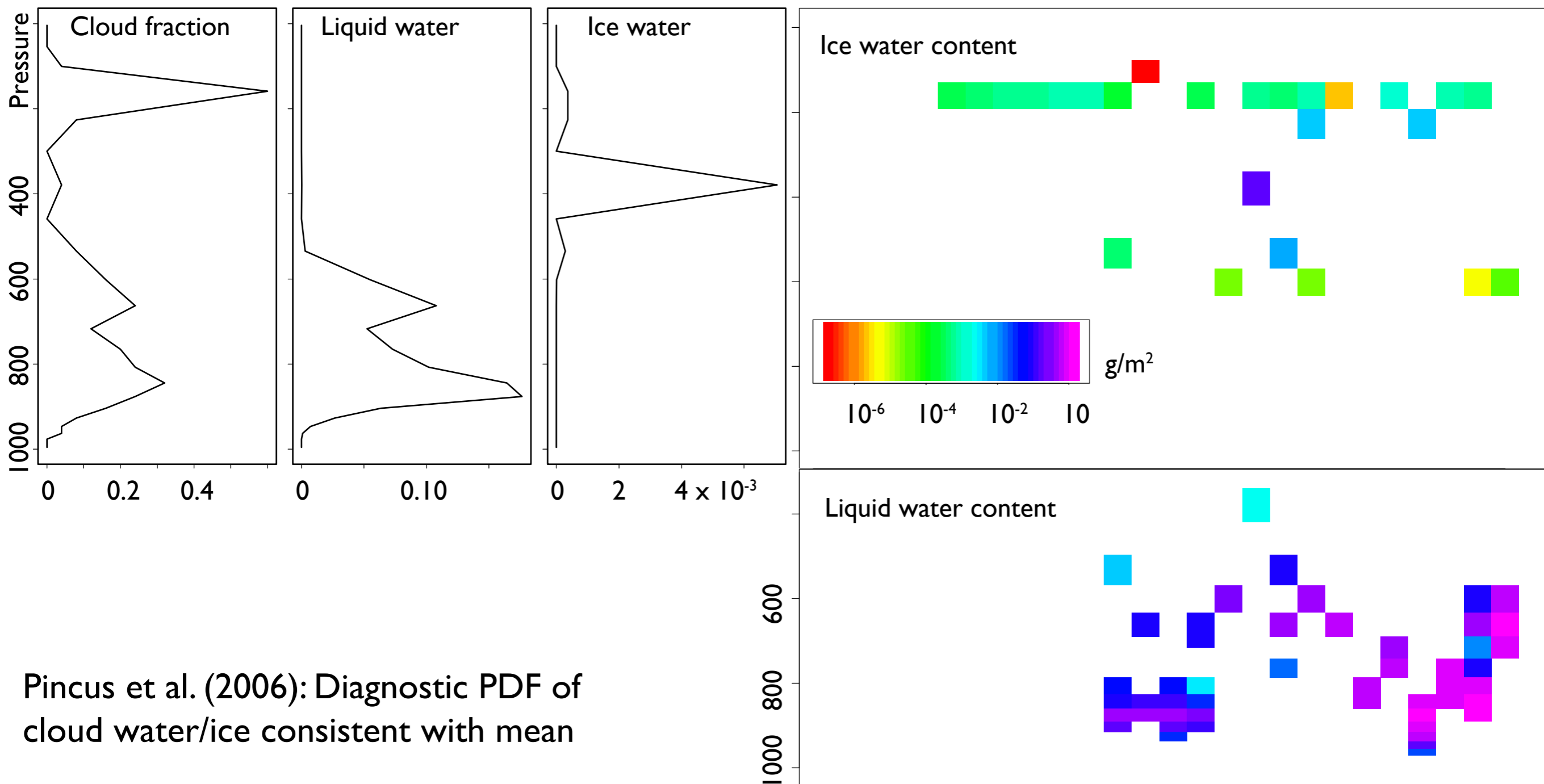
- observational process

These are embodied in “instrument simulators” that operate on subcolumns

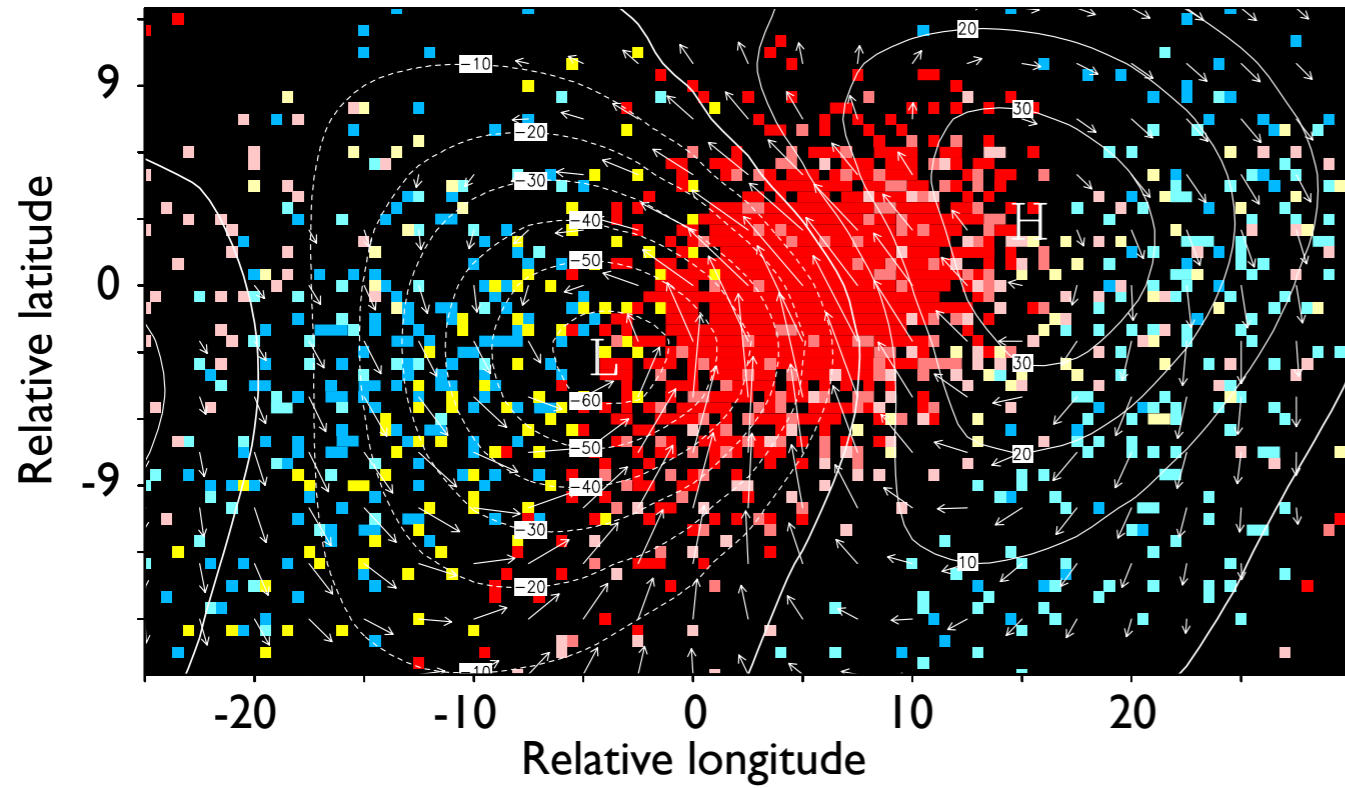
Sampling model state to treat fractional cloudiness/masking



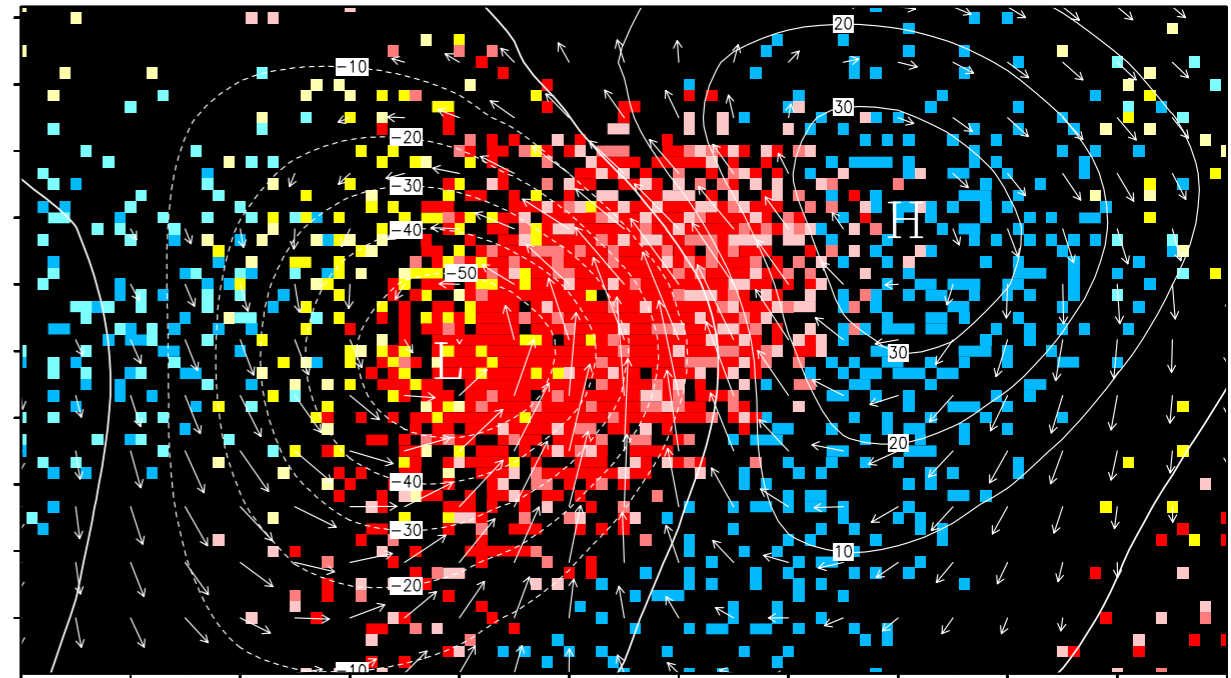
Sampling model state to treat fractional cloudiness/masking



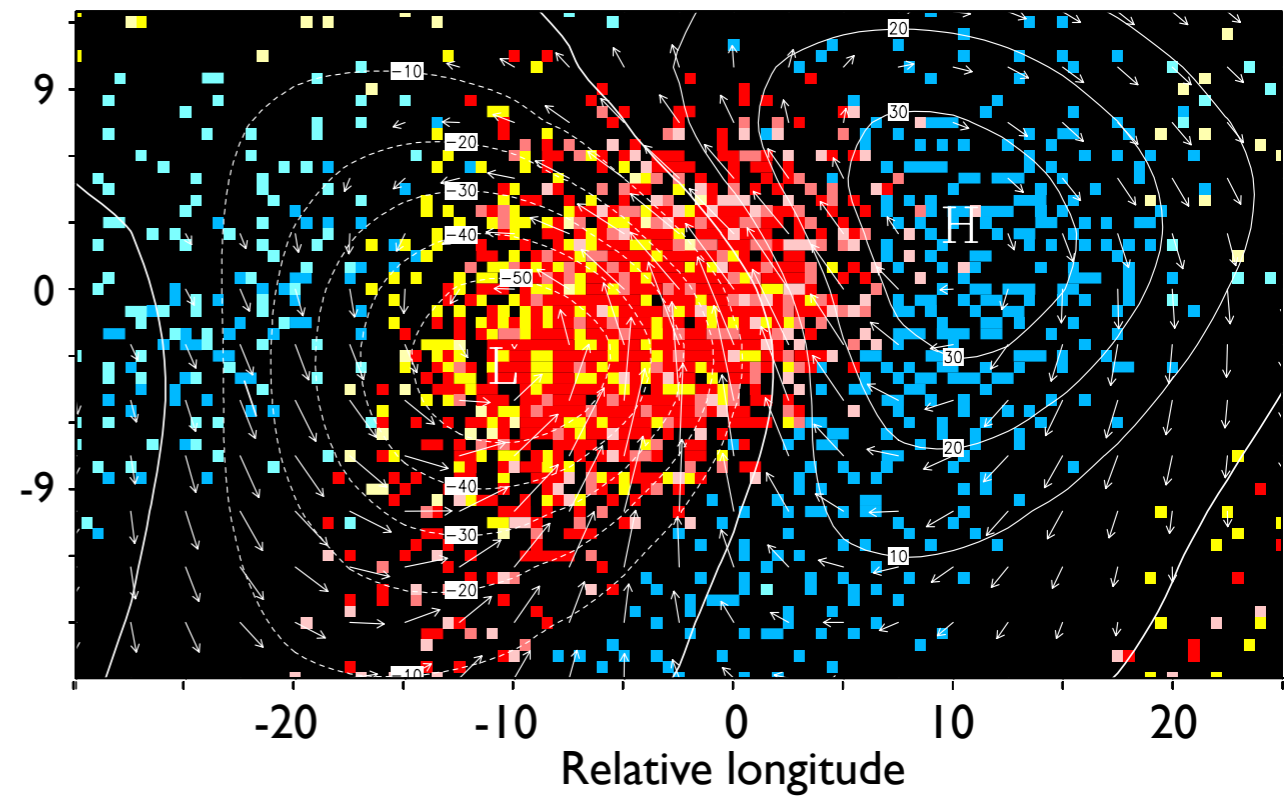
ISCCP



ECMWF



ECMWF (IR cloud top)



After Klein and Jakob, MWR, 1999

A MODIS simulator for climate models (i)

Accepts sub-column inputs of $r_{e(l,i)}(z)$, $\tau_{(l,i)}(z)$ or $q_{(l,i)}(z)$

Provides subcolumn estimates of

$$p_c = \int_{\text{TOA}}^{\tau=1} p(z) \sigma_c(z) dz \quad (\text{when } > 700 \text{ mb, use ISCCP IR})$$

$$P = \int_{\text{TOA}}^{\tau=1} P(z) \sigma_c(z) dz \quad (\text{can be “undetermined”})$$

$$\tau = \int_{\text{TOA}}^{\text{sfc}} \sigma_c(z) dz \quad (\text{no errors, as ISCCP simulator})$$

$$r_e = F^{-1}(F(r_e(z))) \quad (\text{pseudo-retrieval based on near-IR fluxes})$$

A MODIS simulator for climate models (ii)

Estimate liquid, ice water path from optical thickness, particle size

Aggregate sub-columns

cloud fractions (total, liquid, ice, high, middle, low)

in-cloud linear means of all quantities

in-cloud logarithmic mean for optical thickness

optical thickness/cloud top pressure joint histogram

(18 statistics total)

A MODIS simulator for climate models (iii)

MODIS simulator distributed as part of the larger COSP package

Available in essentially every GCM,
though MODIS output is not required for CMIP5

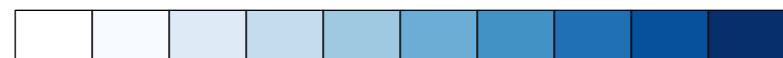
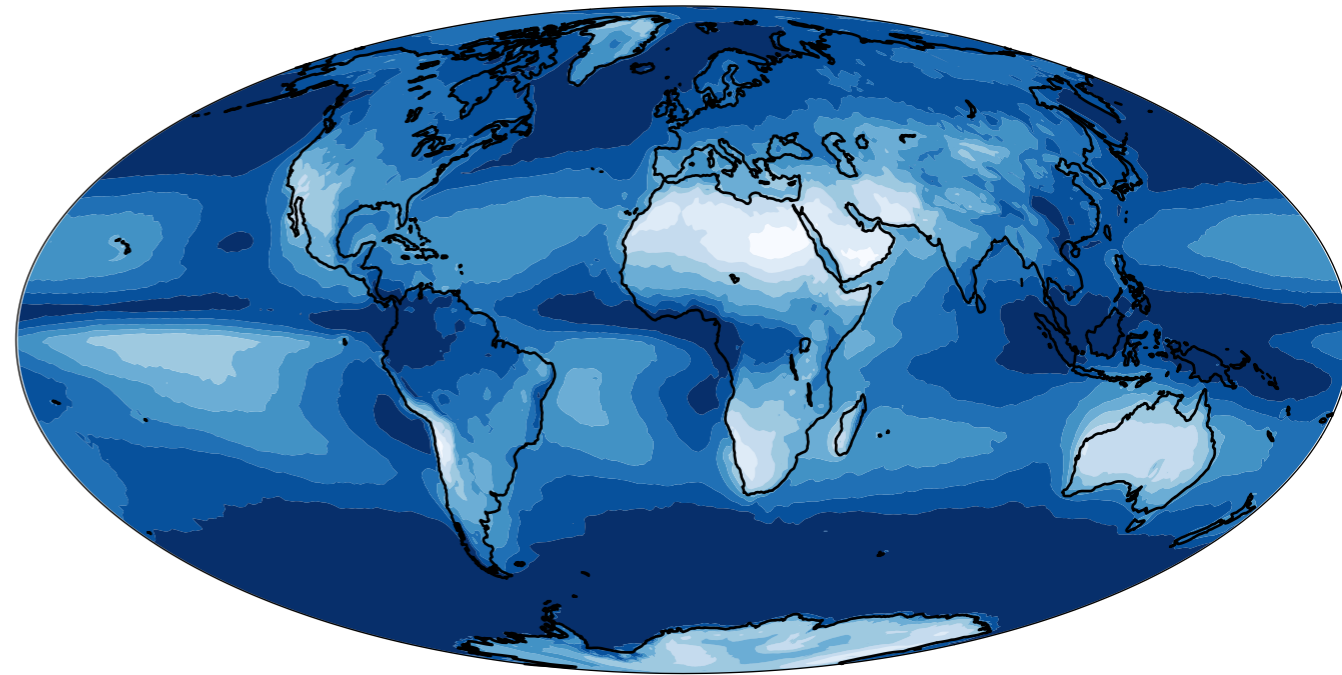
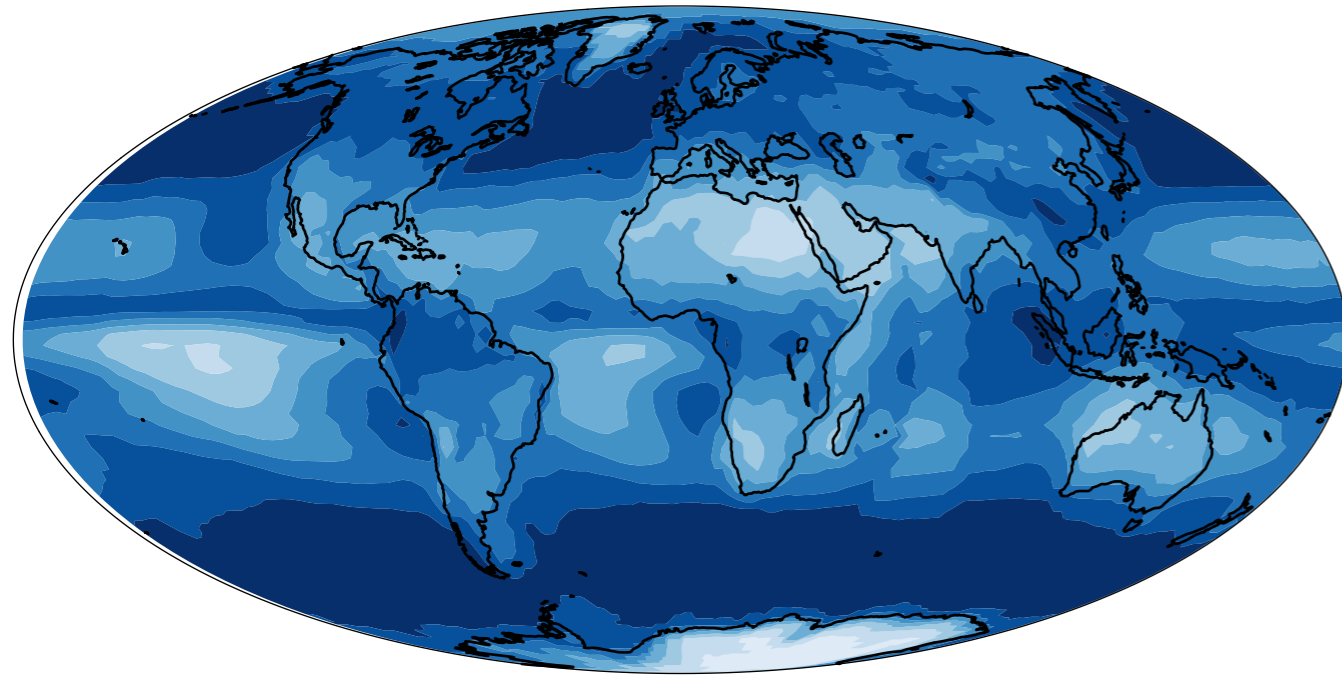
We provide a customized data set for comparisons

Included results from cloud mask and cloud retrievals -
and that's where the fun begins

How much of the planet is cloudy?

ISCCP: 66%

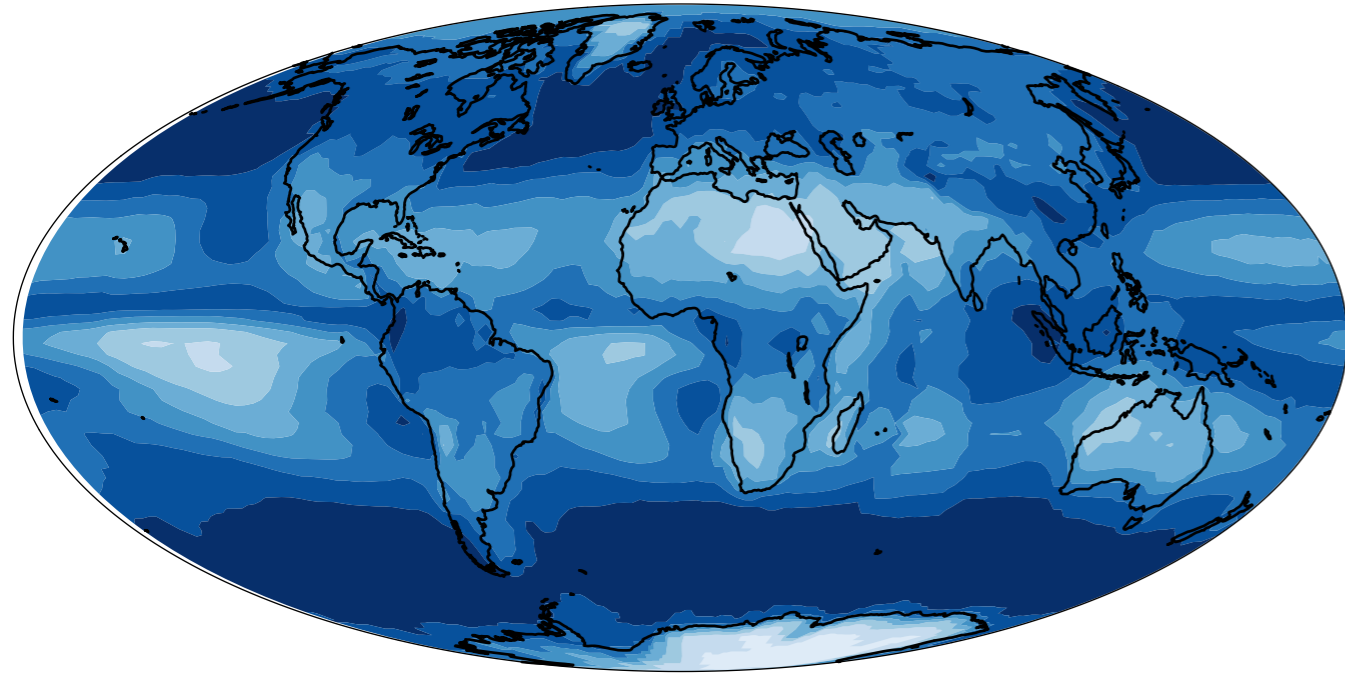
MODIS mask: 67%



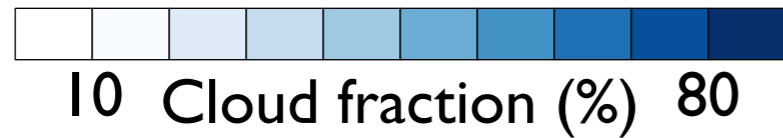
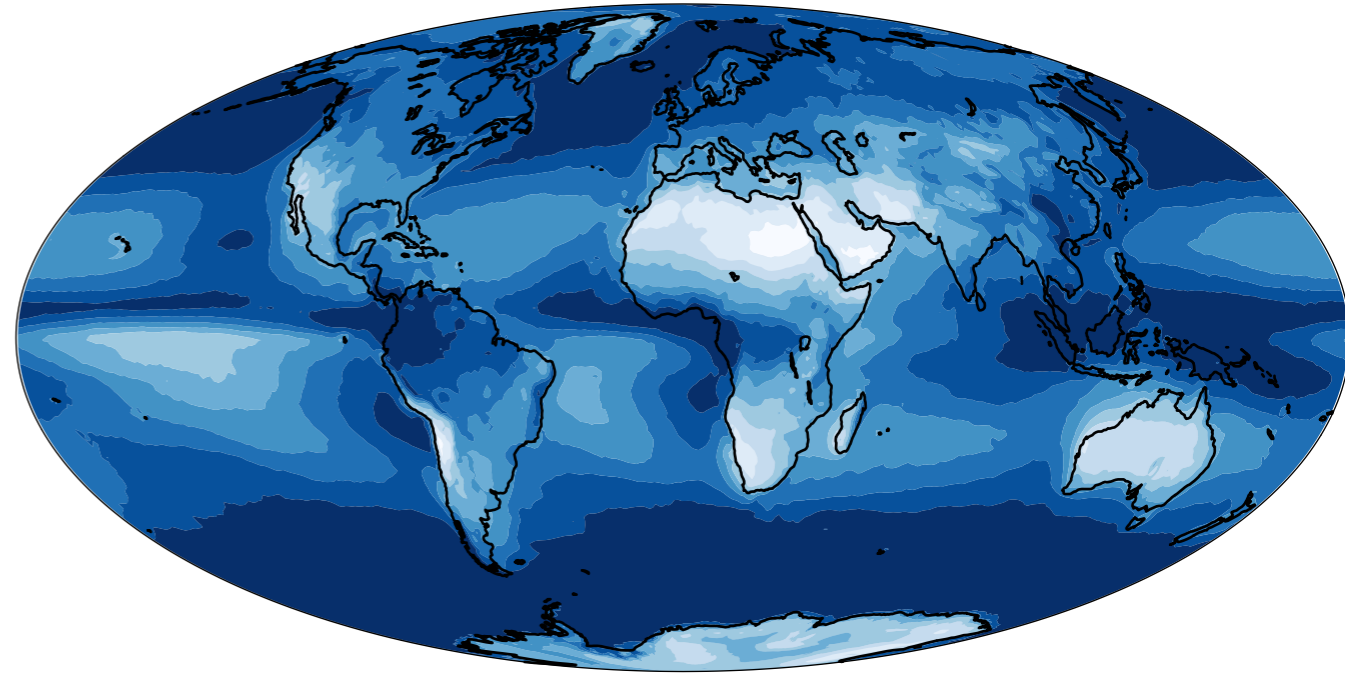
10 Cloud fraction (%) 80

How much of the planet is cloudy?

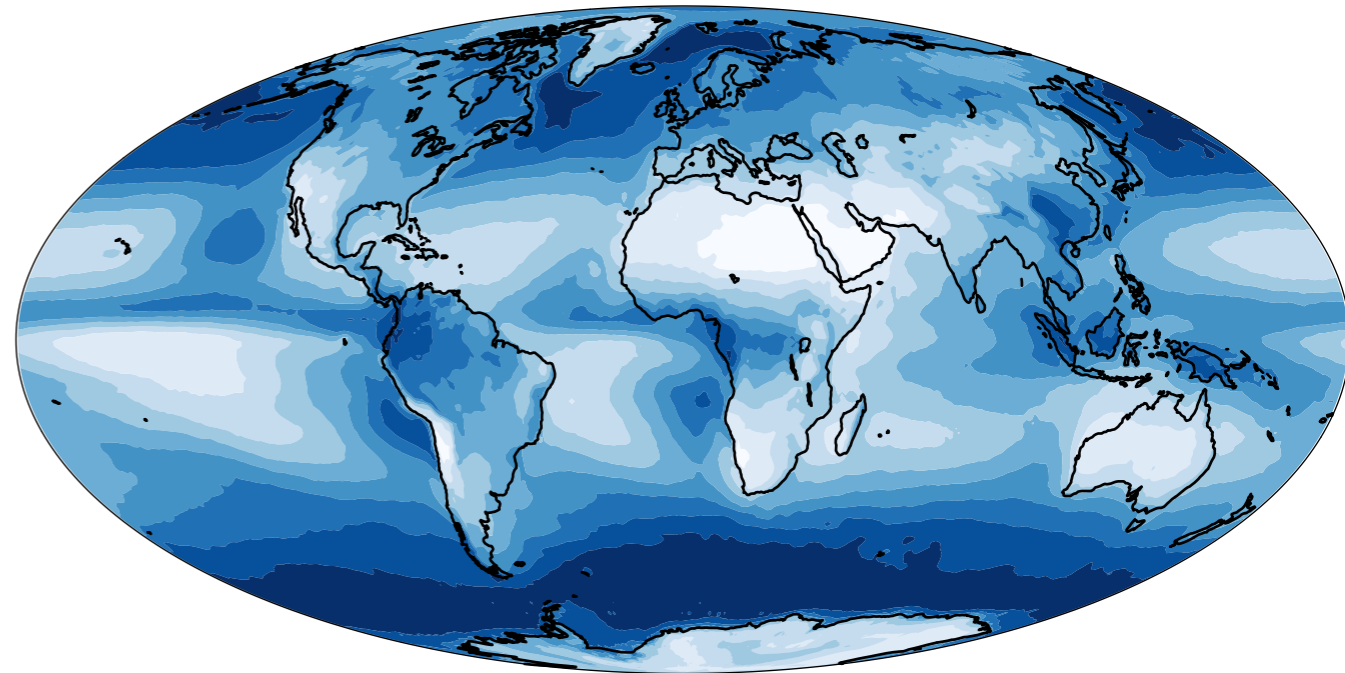
ISCCP: 66%



MODIS mask: 67%



MODIS retrievals: 50%



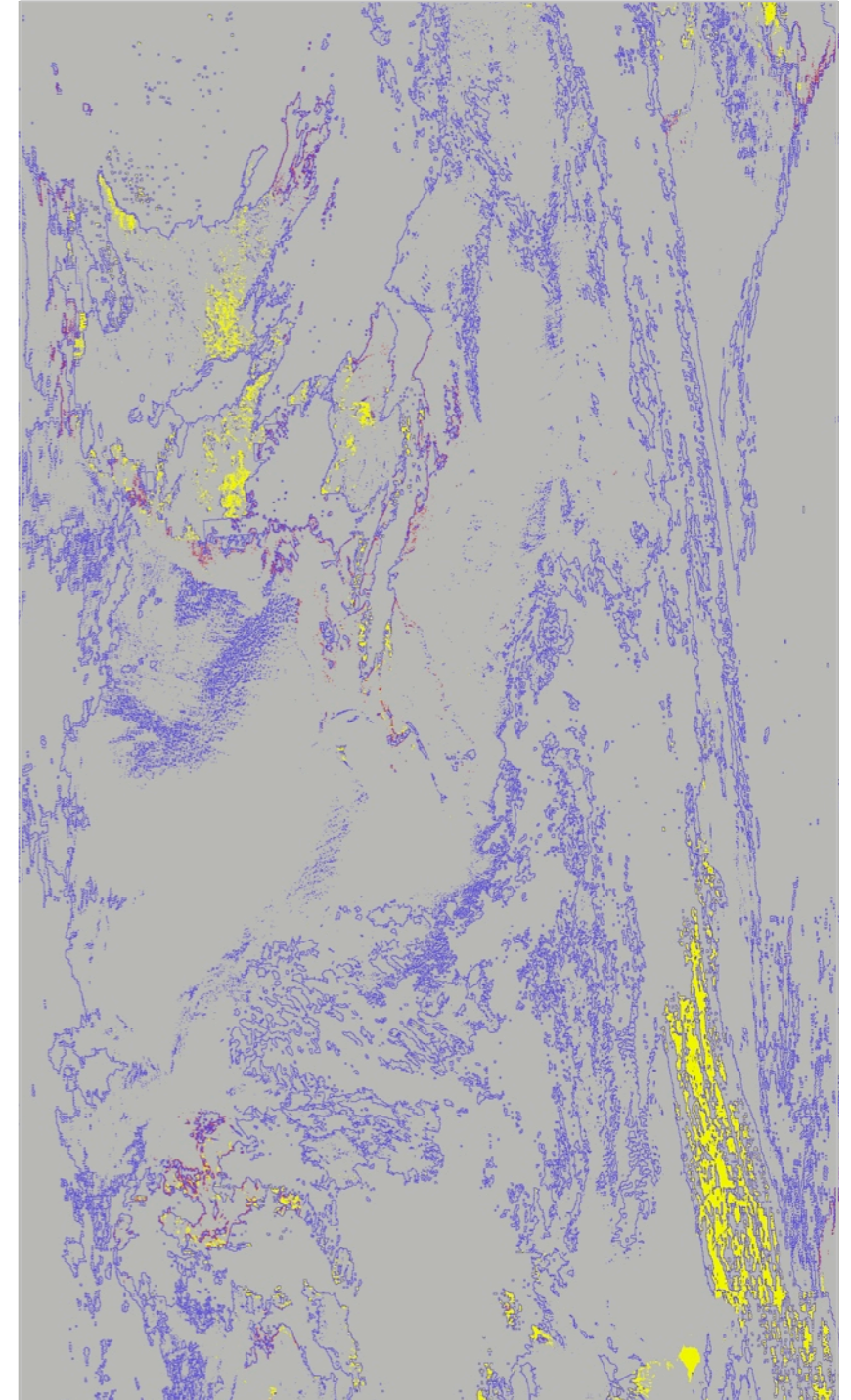
SWIR composite










Cloud Mask overall conf.



“Clear Sky Restoral”



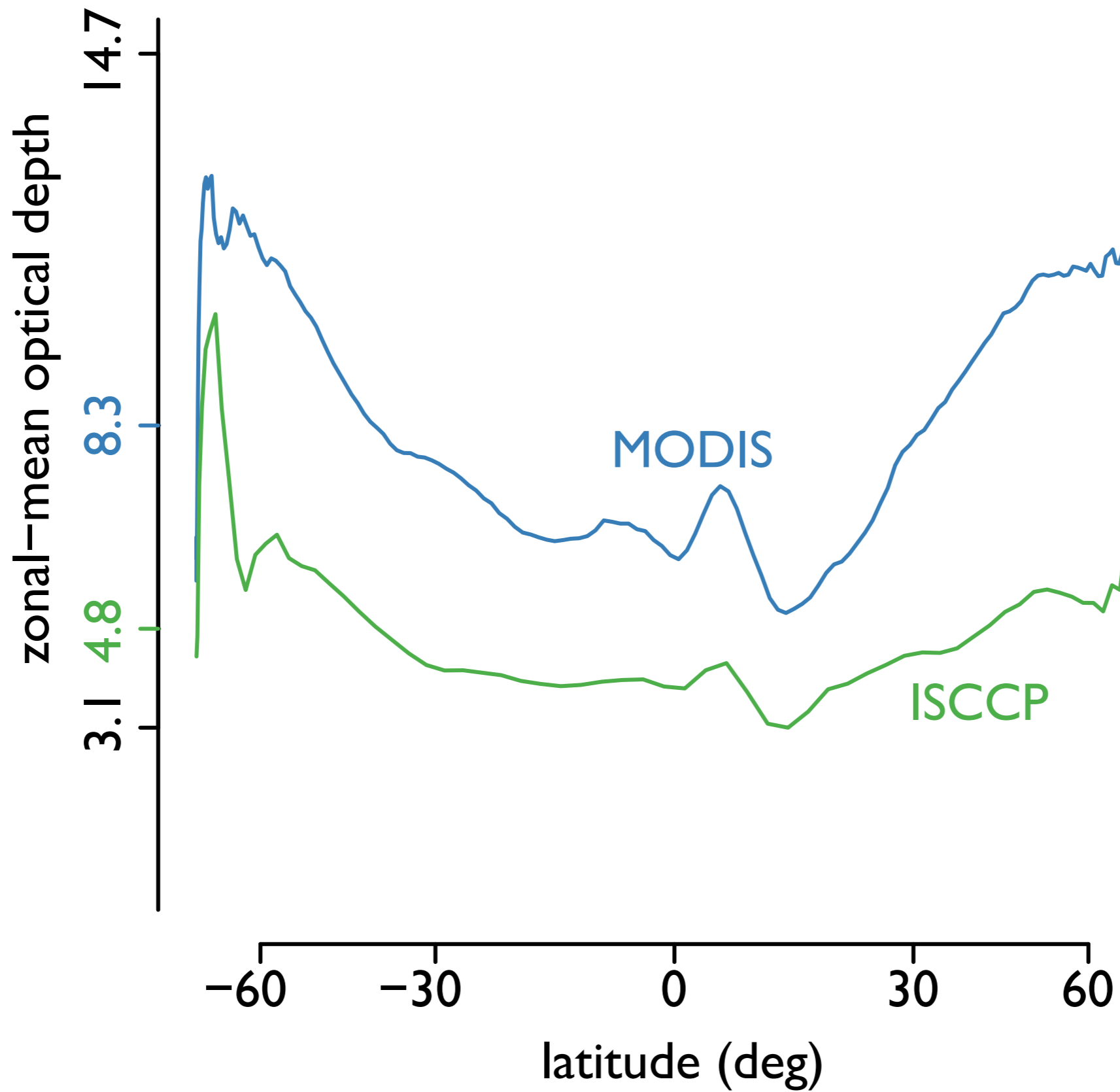
-  probably clear
-  clear
-  cloudy
-  probably cloudy

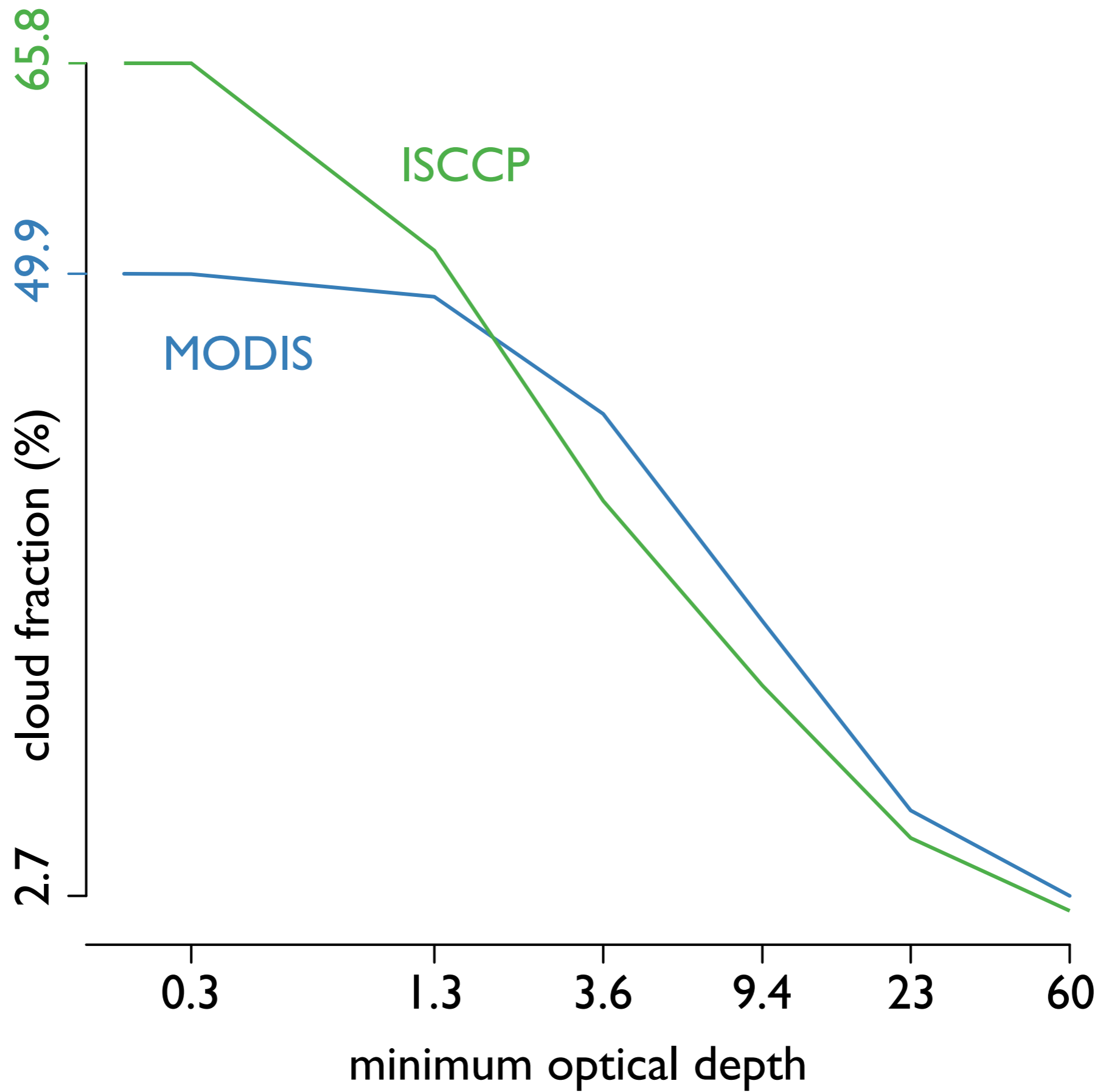
-  spatial/spectral tests
-  edge detection
-  250m cloud mask

Clear-sky restoral was introduced in Collection 5

One practical goal was to reduce the very large particle sizes obtained from MODIS 2.1 μm observations, but...

Clear-sky restoral didn't change average particle size values much because retrievals at cloud edges were failing



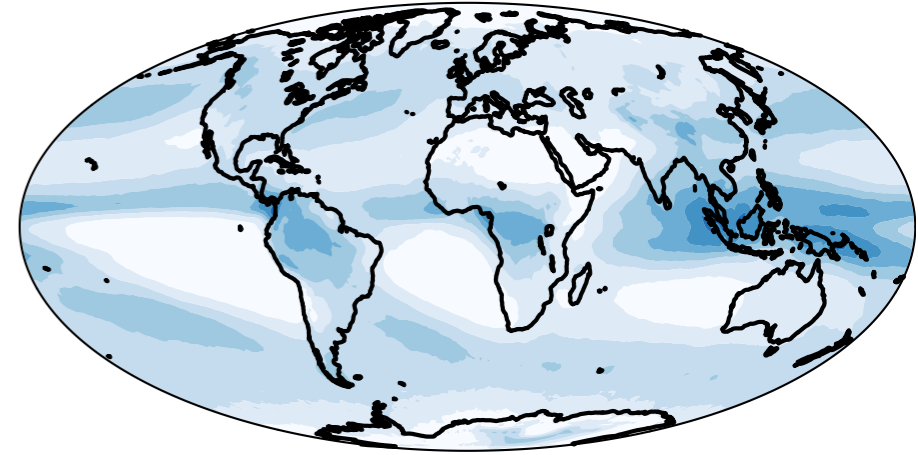
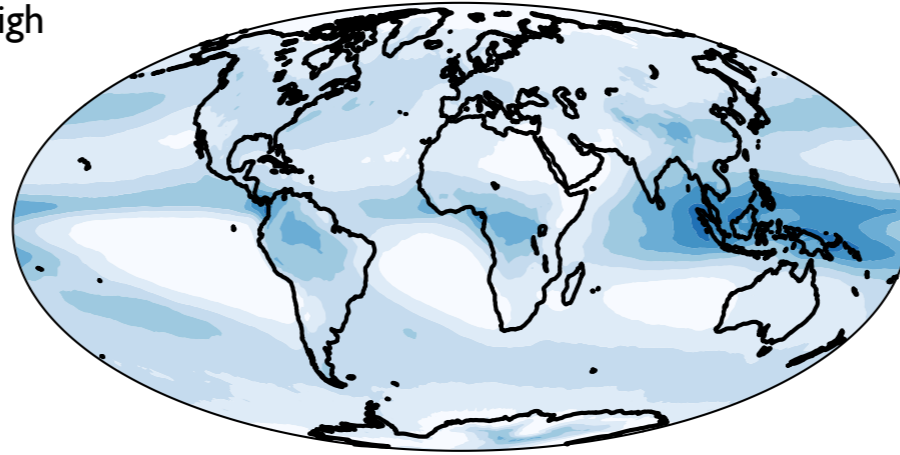
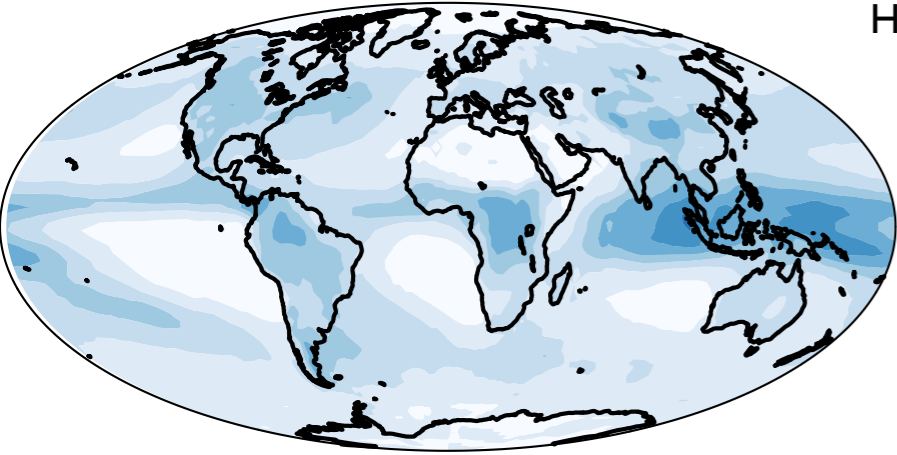


ISCCP

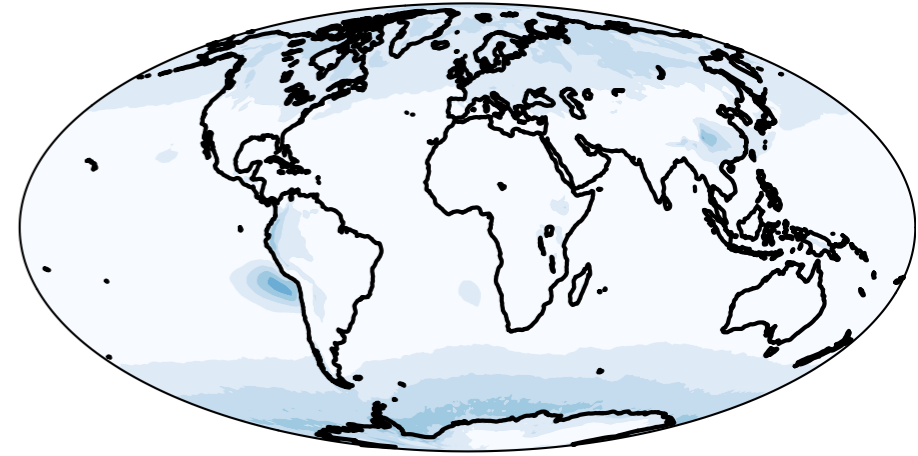
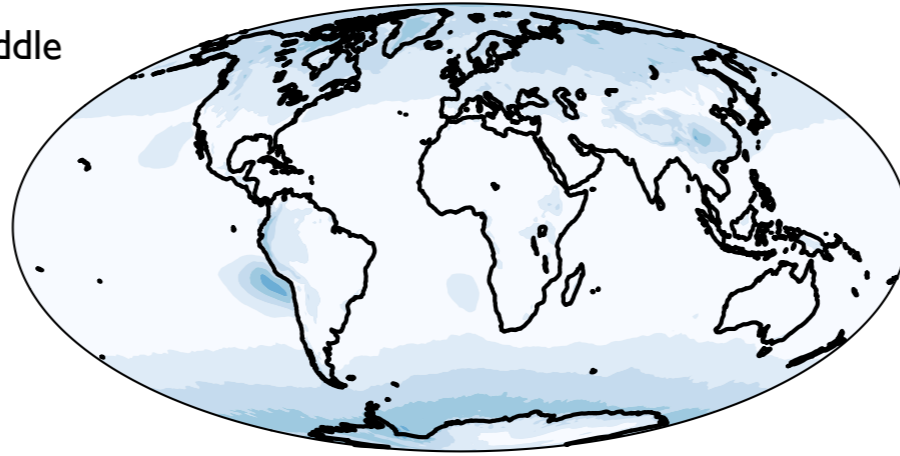
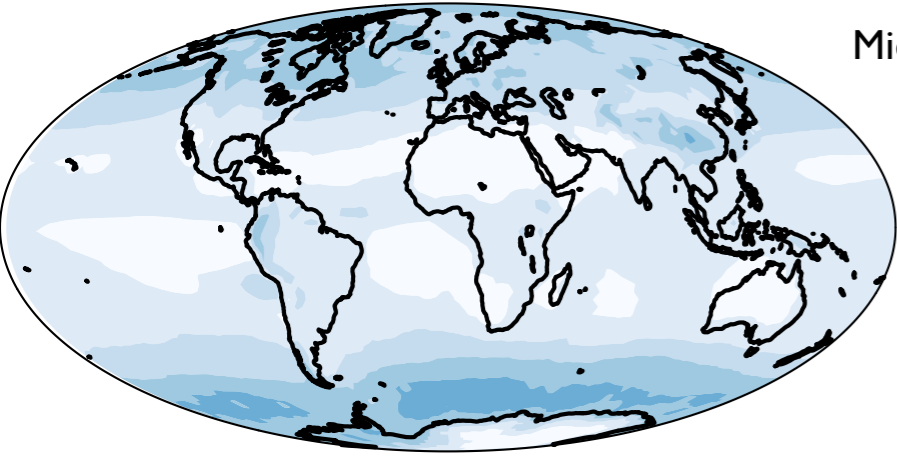
MODIS mask

MODIS retrievals

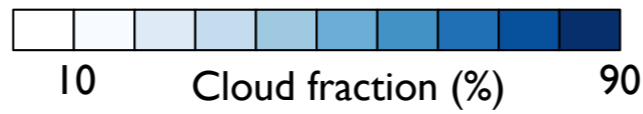
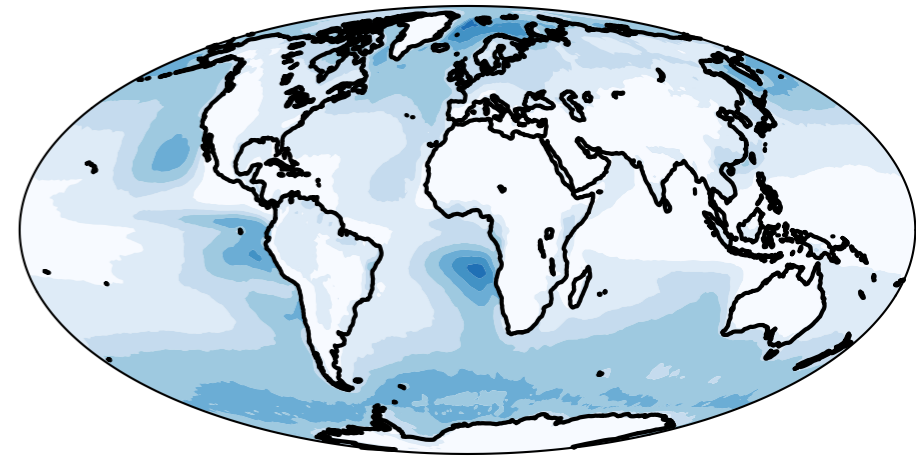
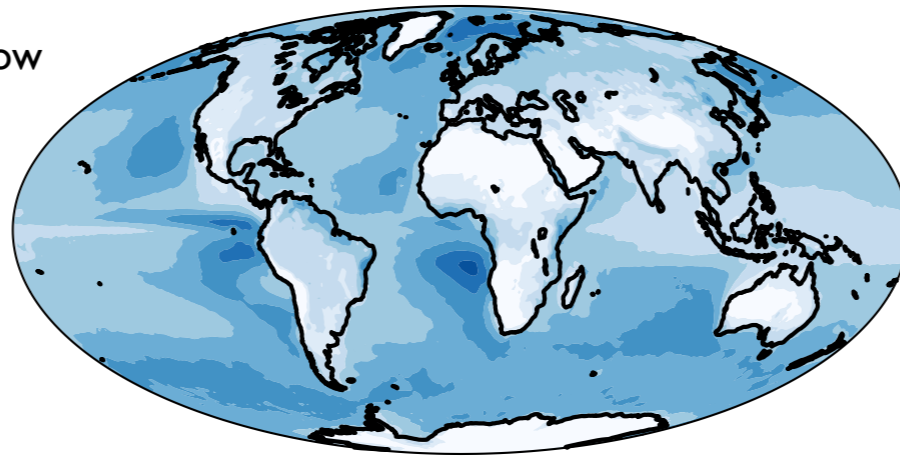
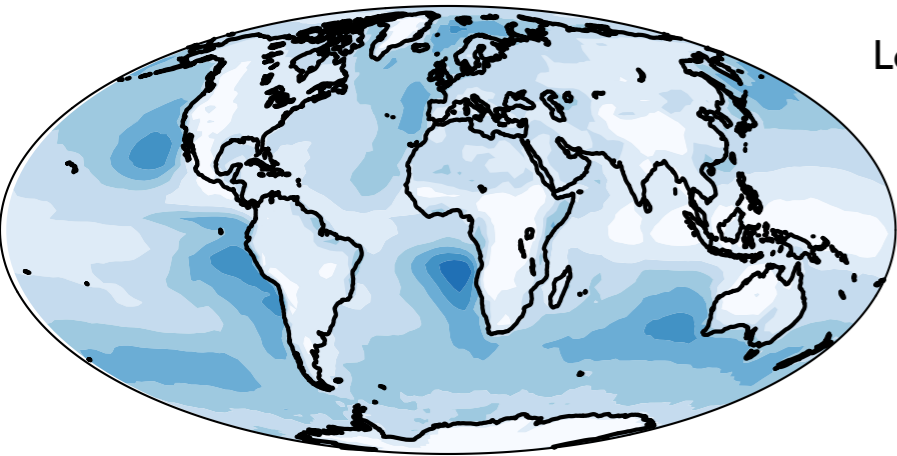
High



Middle



Low



Observation

Pixels are removed by clear-sky restoral mostly because they are near cloud edges or are inhomogeneous at 250 m scale

This population is

nearly all the clouds observed by ISCCP with $\tau < 1.3$

assigned high cloud top pressure by MODIS but distributed through the atmosphere by ISCCP
($\sim 1/3$ are consistent with failed retrievals by ISCCP)

Interpretation

Roughly 15% of the planet is covered by clouds less than 1 km in size

Omitting these pixels leads to truncation errors

Literal interpretations of retrievals is inappropriate

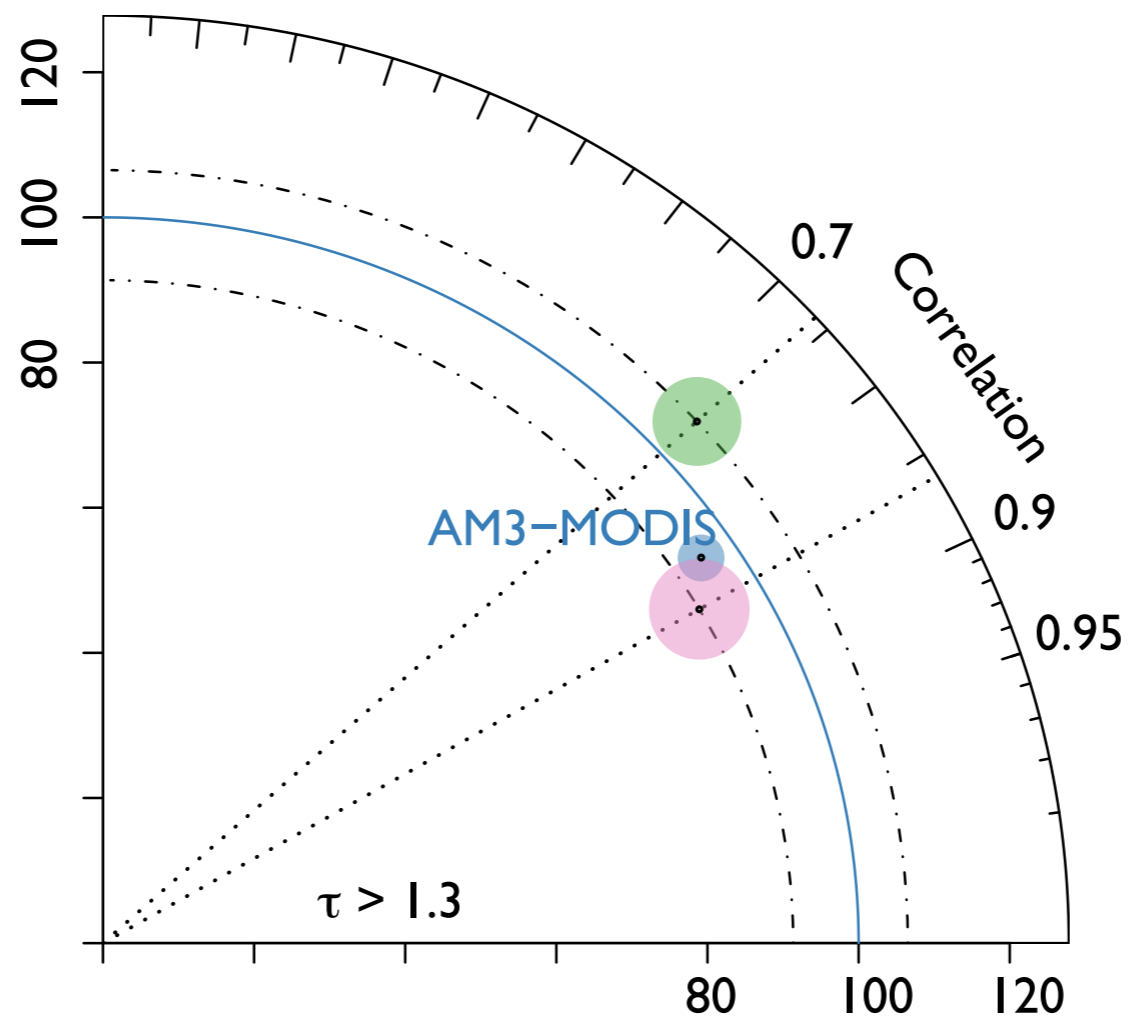
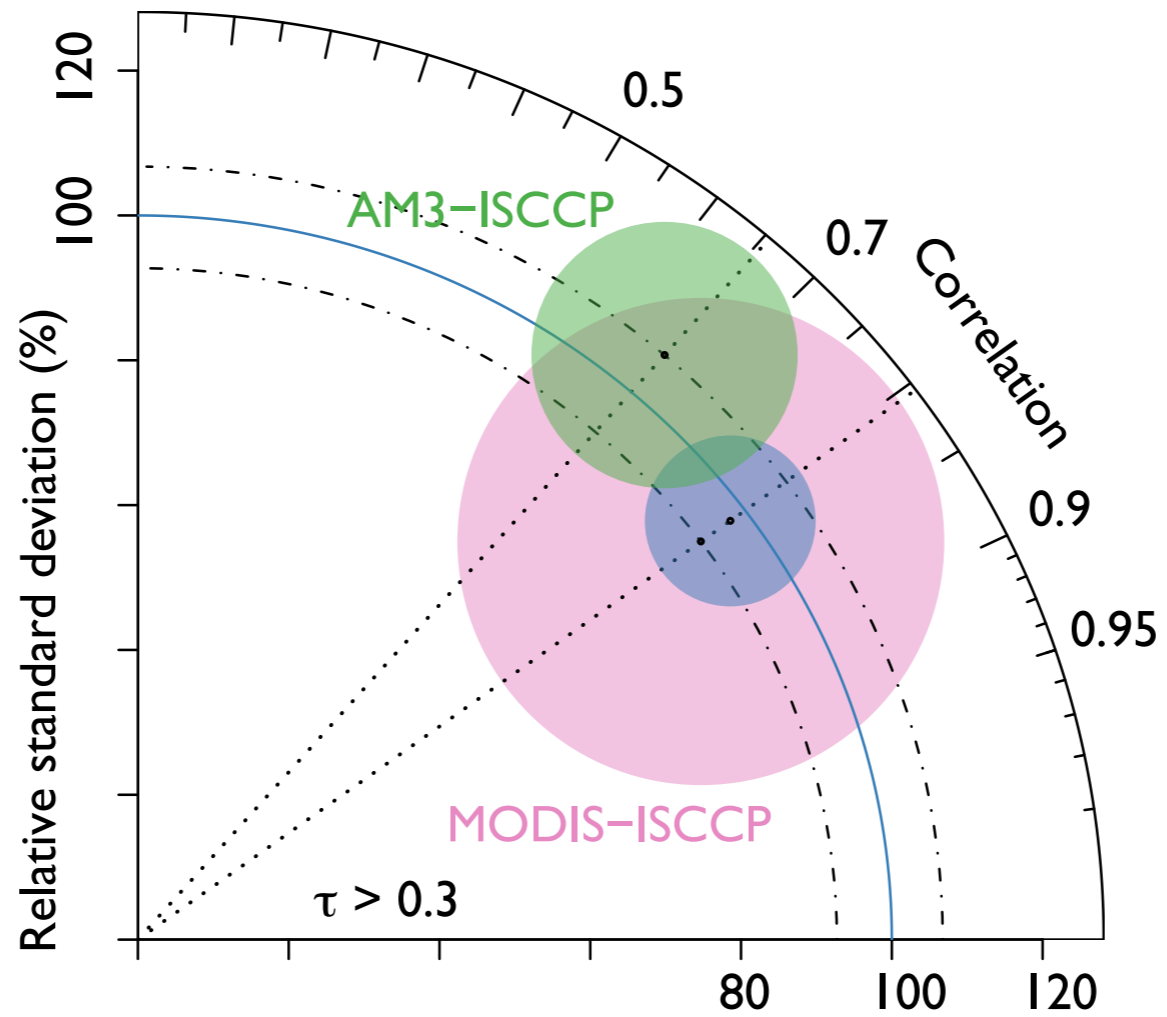
Implication

Cloud fraction estimates explicitly depend on detector resolution and sensitivity

Large-scale models have no concept of spatial scale below the grid size

Total cloudiness is a fragile basis for comparison

Comparisons among observations (and between models and observations) are fair only when the same population is included



Working with the climate modeling community means

doing some translation

understanding our observations more fully

acknowledging when we simply can't speak the same language