# Global Cloud Property Continuity from MODIS to Suomi-NPP Sensors

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Three topics:

MODIS-HIRS monthly mean analysis for month of March over record

Construction of 13.3-µm channel based on VIIRS-CrIS data fusion

**Issues for Atmosphere Team Breakout** 

Joint MODIS-Suomi NPP Science Team Meeting May 2015

# MODIS-Aqua: Nighttime Monthly Mean of High Cloud Frequencies for March from 2003-2015



# MODIS-Aqua: High Cloud Frequencies for March 2015



MODIS 2015 March DN High Cloud Frequency

# Percentage difference of (March 2015 – Monthly Mean) High Clouds from MODIS Aqua

MODIS 2015 March Minus 2003-2015 March DN High Cloud Frequency



# HIRS Nighttime Monthly Mean of High Cloud Frequencies for March from 1989–2013

UW-HIRS Mean 1989-2013 March Night High Cloud Frequency





# MODIS-Aqua: Nighttime Monthly Mean of High Cloud Frequencies for March from 2003-2015



# Percentage difference of (March 1997 – Monthly Mean) High Clouds from HIRS

UW-HIRS N14 March 1997 Minus Mean 1989-2013 March Nighttime High Cloud Frequency



# Percentage difference of (March 2015 – Monthly Mean) High Clouds from Aqua MODIS



MODIS 2015 March Minus 2003-2015 March DN High Cloud Frequency



# Note what happened in following year: 1998 HIRS High Cloud Frequency

UW-HIRS N14 March 1998 Minus Mean 1989-2013 March Nighttime High Cloud Frequency



#### El Nino-La Nina Years and Intensities



Shakespeare: What's past is prologue...?

http://ggweather.com/enso/oni.htm

# VIIRS and MODIS IR spectral bands







### **Different Approaches to Linking Imager and Sounder**

Approach 1: Perform analysis for sounder FOV as first step

Use CTP from sounder as first guess for imager-based optimal estimation

Approach 2: Data fusion statistical approach to construct 13.3 µm at imager resolution

Use combination of IR window and 13.3-µm channels in optimal estimation

Potential application to other polar-orbiting platforms

Sensor	Swath Width (km)
	2800
HIRS	2200
	2330
AIRS	1650
	3040
CrIS S-NPP	2200
AVHRR Moton A/R	2800
HIRS/IASI	2200

## Decadal heritage with 15-µm CO<sub>2</sub> channel data

- Continuity: HIRS record dating back to 1978
- Infer CTP for optically thin ice clouds (Menzel et al. 2008)
- Detection and analysis of multilayered clouds (cirrus over water cloud; Baum et al. 1995)
- For cloud phase, separating low from high clouds (Baum et al. 2012)
- For optimal estimation, use of even a single 15-µm channel greatly limits the solution space for optically thin cirrus (Heidinger et al. 2010)



Baum et al. 1995: Satellite remote sensing of multiple cloud layers. J. Atmos. Sci., 52, 4210-4230. Baum et al. 2012: MODIS cloud top property refinements for Collection 6. J. Appl. Meteor. Clim., 51, 1145-1163. Heidinger et al. 2010: Using CALIPSO to explore the sensitivity to cirrus height in the infrared observations from NPOESS/VIIRS and GOES-R/ ABI. J. Geophys. Res., **115**, D00115, doi:10.1029/2009JD012379. Menzel et al. 2008: MODIS global cloud-top pressure and amount estimation: algorithm description and results. J. Appl. Meteor. Clim., 47, 1175-1198.

# **Statistical Reconstruction**



Cross et al., 2013: Statistical estimation of a 13.3-µm Visible Infrared Imaging Radiometer Suite channel using multisensor data fusion. *J. Appl. Remote Sens.* **7** (1), 073473, doi: 10.1117/1.JRS.7.073473.

Statistical construction of a high spatial resolution 13.3-µm MODIS channel from AIRS



Scene over eastern Atlantic Ocean on April 17, 2015 at 1435 UTC

## Radiance Differences Between Real and Constructed 13.3-µm channel



### CrIS FOVs Superimposed on VIIRS Swath



Scene over eastern Atlantic Ocean on April 17, 2015 at 1440 UTC

# VIIRS Constructed 13.3-µm Channel



# Now focus on 5°x5° region



#### CrIS Resolution vs. Constructed 13.3-µm Channel



What would we rather use for retrievals?

# Comparison of MODIS to VIIRS 13.3-µm Radiances

April 17, 2015



1435 UTC

1440 UTC

#### About the statistical construction approach

# Not rocket science, it's computer science

### Pros:

- No striping, noise, or other artifacts
- Response function same as for MODIS-Aqua
- Hyperspectral IR data are well calibrated
- Do not have to account for gaps between sounder FOVs

#### Cons:

- Radiance differences increase outside of sounder swath
- Requires aligning imager and sounder granules

Radiance differences are about 1-2% of the total (~1°K/typical scene)

Note: this approach works only for the 13.3- $\mu$ m channel – it can not be used to construct any of the IR water vapor channels or a different 15- $\mu$ m CO<sub>2</sub> channel

# **Atmosphere Team Breakout Session**

What is meant by "continuity"?

Availability of MVCM and potentially a VIIRS simulator for team

Data format(s)

Calibration/Validation

Level-3: Data filtering, aggregating, and gridding

ATBD preparation and review

Topical groups are being formed to facilitate some of these goals as part of the 1<sup>st</sup> International Cloud Working Group (ICWG-1)

# The Ist International Cloud Working Group

Will be held in Lille, France in May 2016

http://www.icare.univ-lille1.fr/crew

#### Anticipated Topical Groups

- Use of Combined Sensors for Cloud Retrievals
- Cloud Modeling
- Cloud Height for Wind Applications
- Cloud Retrievals over Snow and Ice Surfaces
- Severe Weather Applications
- Validation Sources
- Assessment of Level-2 Passive Imager Cloud Parameter Retrievals
- Assessment of Retrieval Uncertainties
- Filtering/Aggregation Methods for Climate Applications
- Assessment of Cloud Parameter Data Records for Climate Studies

### In summary

Our approach fuses data from two sensors (imager + sounder) to build a high spatial resolution 13.3-µm band.

This 13.3-µm band is used subsequently for CTH and IR phase, mitigating some of the impact caused by lack of IR sounding bands on VIIRS.

This approach may also prove useful for historical and future platforms.

Cloud product continuity assumes the ability to demonstrate that there is consistency over space and time in products from different sensors and teams...even between different versions by the same team. The issue is choosing a straightforward way to compare the same parameter in different data products.

The ICWG-I will provide a platform for the community to decide how to filter and aggregate each parameter to promote product comparisons.