

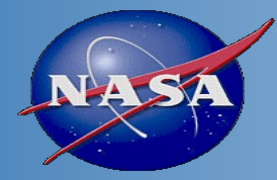


Algorithm Delivery and Integration

Carol C Davidson

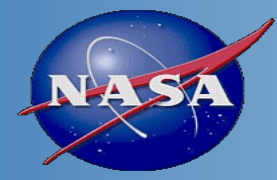
MODIS/VIIRS Software Testing and Integration Team Lead

Science Systems and Application Inc.



Overview

- GitLab
- Software Delivery Process
- Software Integration
- VIIRS Collections C2 vs C1
- MODIS Collections C61 vs C7
- Migration of MODIS C61 PGEs to C7



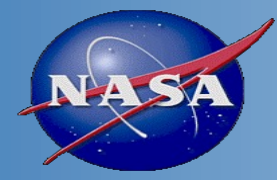
GitLab

- Changing from subversion to GitLab for housing source code repository
 - MODIS C6.1 and VIIRS C2: Transition to Gitlab in progress (~80% completed)
 - Future MODIS C7 and VIIRS C2/C3: Science teams to deliver through Gitlab
 - In house Libraries, science codes, and third-party libraries
 - CentOS7 and Ubuntu supported currently, but will become all Ubuntu
- Science Team on-boarding for future deliveries (MODIS C61/C7 and VIIRS C2/C3) through GitLab
 - STIG will hold on-boarding sessions for science teams
 - GitLab access via EarthData Login (EDL) and NASA Launchpad (*more details available in backup slides*)
 - Interface for STMs to use for making code deliveries.
 - Learning Resources
 - Account access/setup go to: [Accounts · Wiki · infrastructure / Help · GitLab \(nasa.gov\)](#).
 - Basics on working with PGE source codes within GitLab [MODAPS / Documentation · GitLab \(nasa.gov\)](#)
 - More detailed User's Guide pdf available as well.



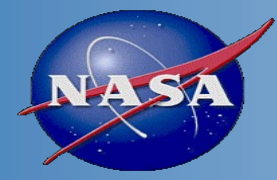
Gitlab Organization

- Code packages are organized into projects within GitLab and projects are organized into groups.
- Top level group is named “MODAPS”
 - Contains projects for third-party libraries, codes shared between MODIS and VIIRS, and documentation.
 - Contains “MODIS” and “VIIRS” sub-groups
- “MODIS” group contains sub-groups “ATMOS”, “Library”, “shared_src”, “LAND”, and “INHOUSE, each of which hold the projects for PGEs and/or shared codes.
- “VIIRS” group contains projects for all PGEs, shared codes, and VIIRS specific libraries, like IDPS and OPS.



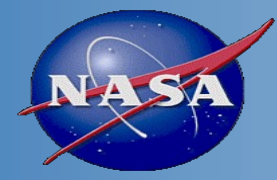
Software Delivery

- Overview of the basic steps for updating/delivering a PGE. (*actual sequence of steps for an example of PGE11 provided in Back up slides*)
 - Determine Project name and branch (i.e, PGE and collection) you want to update. For example, MODIS PGE11 for C6.1.
 - Clone the project to the command line
 - Switch to the C61 branch.
 - Create a new branch for your updates; the new branch will be based on the C61 branch you are sitting on.
 - Switch to the new branch you created and integrate your changes. Build and test the updates and when satisfied, send them back to the repository.
 - Verify code pushed back built successfully within GitLab and resolve issues if it did not.
 - Submit update for merging/integration by SSTG by creating a Merge Request



Software Integration and Unit Test

- SSTG steps with STM delivery:
 - Create a forked copy of the project to work in.
 - Pull the STM delivery branch to forked copy/check that branch out.
 - Review the STM delivery. Implement updates needed in PGE perl scripts for inputs, outputs, runtime parameter settings or production rules.
 - Document changes in PGE HISTORY file.
 - Commit and push any changes made to working copy in GitLab and verify successful build/deploy.
 - Create a tag of the new version and use to execute command line and MODAPS tests with.
 - If all tests complete successfully and no concerns, update original merge request with test information and approve merge request as the “reviewer”
 - CM completes merge and tagging of PGE



VIIRS C1 vs C2

- C1 PGEs currently in subversion, (planned for migration to GitLab at a later time ?)
- C2 PGEs ported to Gitlab
 - 85% of existing land PGEs migrated to GitLab and successfully build to execute on Ubuntu system.
 - Ubuntu version of SNPP C2 and JPSS1 C2.1 Geolocation deployed from Gitlab in operational processing
 - All C1 land PGEs updated to use NASA Geolocation and L1B data, both NetCDF4.2 format, as input.
 - Standard products generated in netcdf4/HDF5/HDFEOS5 format
 - Includes improvements to Land SIPS CloudMask, changes to metadata to be consistent with MODIS products.



MODIS C61 VS C7

- Output file format: NetCDF (HDF-EOS5) vs HDF4 (HDF-EOS2)
 - C61 : HDF4 format, support HDF-EOS Swath and Grid
 - C7 : HDF5 format, CF-1.6 compliant, support HDF-EOS Swath and Grid
- Metadata:
 - C61: nested within 'CoreMetadata.x' attribute; generated using SDP Toolkit and MCF
 - C7: global attributes for each metadata, Doesn't use SDP Toolkit.
- CF-compliant
 - C7 output files will be CF compliant and can be georeferenced by NetCDF data viewers or tools
 - L2 Swath data: latitude and longitude are resampled and added for different sizes of data in the file by the C7 libraries.
 - L3 Grid data: projection parameter attributes will be added by the C7 libraries.
- PCF file
 - C7: "key = value" format
 - C7: LUN number -> LUN string. E.g. 600000 -> MxD03
- MCF file
 - C7: "name|mandatory|type|num_val|value" format
- Toolkit
 - C61: Uses SDP Toolkit
 - C7: New API-trans and SDP-utils libraries developed by LDOPE/SSTG.



MODIS C7 VS C61

C61 metadata

```
OBJECT      = SHORTNAME
NUM_VAL     = 1
VALUE       = "MOD03"
END_OBJECT  = SHORTNAME

OBJECT      = VERSIONID
NUM_VAL     = 1
VALUE       = 61
END_OBJECT  = VERSIONID
```

C7 metadata

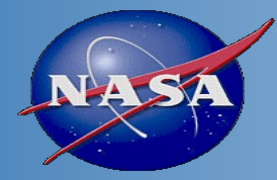
```
LocalVersionID = 7.0.7
LongName = MODIS/Terra Raw Radiances in Counts 5-Min L1A Swath
Max Earth Frames = 1354
Max SD Frames = 50
Max SV Frames = 50
Missing Packets = 0
NOT EMPTY196265598 = NOT EMPTY
NorthBoundingCoordinate = -59.029475
Number of Scans = 203
OrbitNumber = 104189
```

C61 MCF File

```
OBJECT = LocalGranuleID
  Data_Location = "PGE"
  NUM_VAL = 1
  TYPE = "STRING"
  Mandatory = "TRUE"
END_OBJECT = LocalGranuleID
OBJECT = ProductionDateTime
  Data_Location = "TK"
  NUM_VAL = 1
  TYPE = "DATETIME"
  Mandatory = "TRUE"
END_OBJECT = ProductionDateTime
```

C7 MCF File

```
ReprocessingActual | TRUE | STRING | 1 |
LocalGranuleID | TRUE | STRING | 1 |
ProductionDateTime | TRUE | DATETIME | 1 |
DayNightFlag | TRUE | STRING | 1 |
LocalVersionID | FALSE | STRING | 1 |
ParameterName | TRUE | STRING | 1 |
AutomaticQualityFlag | TRUE | STRING | 1 |
AutomaticQualityFlagExplanation | TRUE | STRING | 1 |
OperationalQualityFlag | FALSE | STRING | 1 |
OperationalQualityFlagExplanation | FALSE | STRING | 1 |
```



Migration of MODIS C61 to C7

How C7 libraries work

The New API-trans and SDP-util libraries developed by LDOPE/SSTG provides HDF4 to HDF5 API implementation for every HDF4 call in the current operational MODIS PGEs.

PGE code

```
#include <stdio.h>
#include "hdf.h"
#include "mfhdf.h"
#include "apiTrans.h"

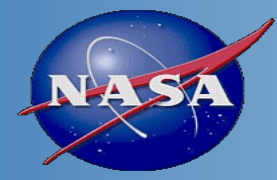
int main(int argc, char *argv)
{
    ...
    int32 id = SDstart(fname, DFACC_RDWR);
    ...
}
```

apiTrans.h

```
#define SDstart(fname, mode) h4to5_SDstart(fname, mode)
```

apiTrans.c

```
int32 h4to5_SDstart(char *filename, int32 access_mode)
{
    if(isHdf4(filename)){
        return SDstart(filename, access_mode);
    }
    else{
        /* implement by HDF5 API*/
    }
}
```



Migration of MODIS C61 to C7

How to convert C61 PGE to C7

- Add "apiTrans.h" to C files which include HDF4 or HDF-EOS2 calls;
- Add compile and link flags to makefile for C7 Libraries (API-Trans and SDP-Utills);
- Modify the Perl script to use new Perl libraries for C7 PCF format;
- Use provided tool to convert MCF files to C7 format;

Note: C61 metadata are nested in a "CoreMetadata" while C7 are saved as global attributes for each of them. If PGE code uses SDP-Toolkit API to read/write metadata then nothing needs to be done; If PGE code parses the "CoreMetadata" string by itself then it will not work in C7.

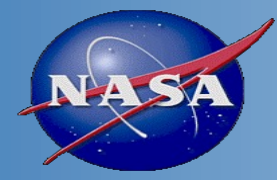


Migration of MODIS C61 to C7

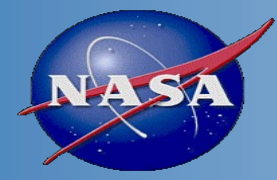
How to update C7 PGE code by science team

- The PGE code is basically the same as C61 – still using HDF4/HDF-EOS2 function calls. Continue using HDF4/HDF-EOS2/SDP-Toolkit APIs if new attributes or SDS are added.
- LDOPE and SSTG will create baseline C7 PGEs by taking operational C7 PGEs and integrating API related changes. STMs focus on scientific changes.

Note: C7 PGEs will be managed by Gitlab. Here is a Wiki how to update a PGE in Gitlab and run tests:
<https://gitlab.modaps.eosdis.nasa.gov/modaps/documentation/-/wikis/home>

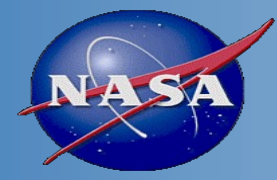


Backup Slides



GitLab Access

- URL for MODAPS GitLab repository is [Projects · Dashboard · GitLab \(nasa.gov\)](#)
- Preferred access method is NASA LaunchPad.
- LaunchPad account holder should request access to the GitLab area via NAMS at <https://idmax.nasa.gov/nams/asset/254154/670356850>
- STMs without LaunchPad accounts may connect using EarthData login.
- For LaunchPad or EarthData, users must be added to appropriate user groups in order to access content.
- SSTG can contact appropriate admin for gaining access needed.



Software Delivery (1 of 4)

- Actual steps for update and delivery using mix of command line and web interface.
 - Clone the MODIS PGE11 project to the command line:
 - `git clone https://GitLab.modaps.eosdis.nasa.gov/modaps/modis/land/pge11.git`
 - Switch to the pge11 directory created, go to the C61 branch so you start with the C61 code stored there:
 - `git checkout C61`
 - Create a new branch identical to the C61 branch for your updates using:
 - `git checkout -b pge11update0422`
 - Integrate your changes and then send them back to the repository using:
 - `git add .` (to add any new files to the repository)
 - `git commit -am "<note about files modified/added/deleted>"`
 - `git push origin pge11update0422`

Continued on next slide



Software Delivery (2 of 4)

- Via GitLab web interface, go to project <https://GitLab.modaps.eosdis.nasa.gov/modaps/modis/land/pge11.git>
- From left hand menu click on “CI/CD” to view pipelines – this is where you verify the code you pushed built successfully.

The screenshot shows the GitLab web interface for the project 'MODAPS / MODIS / LAND / PGE11'. The left-hand navigation menu is open, and the 'CI/CD' section is selected, showing 'Pipelines'. The main content area displays a table of pipeline runs. All runs are in a 'passed' state.

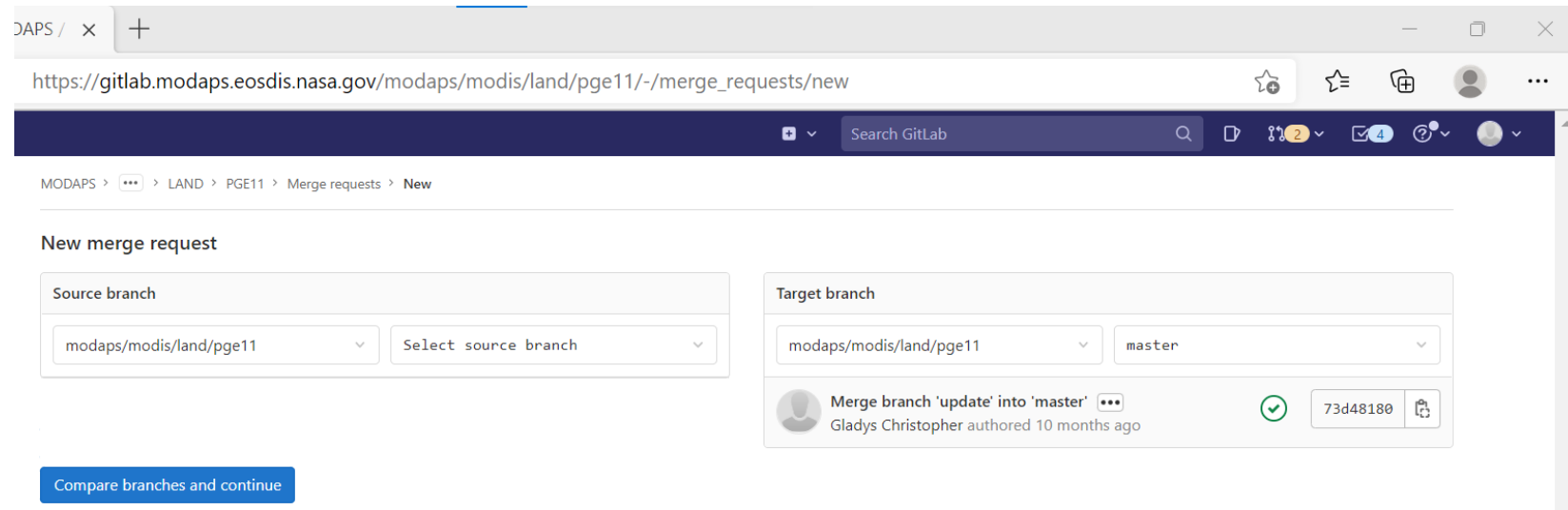
Status	Pipeline	Triggerer	Stages
passed	Merge branch 'update' into 'master' #64207 L1B_C7_TEST -> 28c5ec08 00:00:50 2 weeks ago	[Avatar]	✓ ✓
passed	Merge branch 'C61_update' into 'C61' #50733 6.4.10-1 -> 24f0cf4b 00:00:48 7 months ago	[Avatar]	✓ ✓
passed	Merge branch 'C61_update' into 'C61' #50731 C61 -> 24f0cf4b 00:00:44 7 months ago	[Avatar]	✓ ✓
passed	Merge branch 'C61_update' into 'C61' #50702 6.4.10-0 -> bda8c5ce 00:00:52 7 months ago	[Avatar]	✓ ✓
passed	Merge branch 'C61_update' into 'C61' #50701 C61 -> bda8c5ce 00:00:51 7 months ago	[Avatar]	✓ ✓

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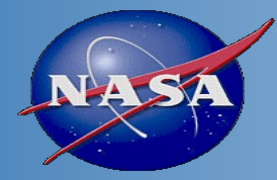


Software Delivery (3 of 4)

- Once pipeline is successful, submit your changes via a Merge Request
- From left hand menu click on “Merge Requests”
- On next page select “New merge request” button.
- On “New merge request” page, select the “source” and “target” branches. For our example, “source” is “pge11update0422”, and “target” is “C61”.
- Click on “Compare branches and continue”



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Software Delivery (4 of 4)

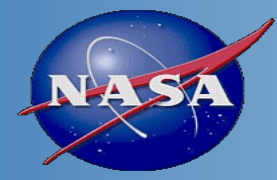
- On next “New merge request” page, fill out information as requested.
 - Title: this should indicate PGE and/or process name and version, for example PGE11 v6.1.20 update
 - Description: summary of changes made and what testing was done.
 - Assignee: select “modiscm”
 - Reviewer: Can be left blank or set to STIG member you communicated with regarding change.
 - Merge options: the “Delete source branch when merge request accepted” is selected by default. Deselect this option if you wish to retain the branch.
 - Click on “Create merge request”

The screenshot shows the GitLab interface for creating a new merge request. The browser address bar shows the URL: https://gitlab.modaps.eosdis.nasa.gov/modaps/viirs/pge999/-/merge_requests/new?merge_request%5Bsource_project_id%5D=17...

The form includes the following fields and options:

- Title:** A text input field with a placeholder "Title". Below it, there is a note: "Start the title with Draft: to prevent a merge request draft from merging before it's ready. Add description templates to help your contributors communicate effectively!"
- Description:** A rich text editor with a "Write" tab selected. The placeholder text reads: "Describe the goal of the changes and what reviewers should be aware of." Below the editor, it says "Markdown and quick actions are supported" and "Attach a file".
- Assignee:** A dropdown menu set to "Unassigned" with a link "Assign to me".
- Reviewer:** A dropdown menu set to "Unassigned".
- Milestone:** A dropdown menu set to "Milestone".
- Labels:** A dropdown menu set to "Labels".
- Merge options:** Two checkboxes: "Delete source branch when merge request is accepted." (checked) and "Squash commits when merge request is accepted." (unchecked).

At the bottom of the form, there are two buttons: "Create merge request" and "Cancel".



Display C7 L2 data in Panoply

Data with different resolution are all georeferenced

Panoply — Sources

Create Plot Combine Plot Open Dataset Remove Remove All Hide Info

Datasets Catalogs Bookmarks

Name	Long Name	Type
▼ Data_Fields	HDFEOS/SWATHS/MODIS_SWA...	—
Band_1KM_Emissive	Band 1KM Emissive	1D
Band_1KM_RefSB	Band 1KM RefSB	1D
Band_250M	Band 250M	1D
Band_500M	Band 500M	1D
EV_1KM_Emissive	Earth View 1KM Emissive Band...	Geo2D
EV_1KM_Emissive_Uncert_Indexes	Earth View 1KM Emissive Band...	Geo2D
EV_1KM_RefSB	Earth View 1KM Reflective Sola...	Geo2D
EV_1KM_RefSB_Uncert_Indexes	Earth View 1KM Reflective Sola...	Geo2D
EV_250_Aggr1km_RefSB	Earth View 250M Aggregated ...	Geo2D
EV_250_Aggr1km_RefSB_Samples...	Earth View 250M Aggregated ...	Geo2D
EV_250_Aggr1km_RefSB_Uncert_I...	Earth View 250M Aggregated ...	Geo2D
EV_500_Aggr1km_RefSB	Earth View 500M Aggregated ...	Geo2D
EV_500_Aggr1km_RefSB_Samples...	Earth View 500M Aggregated ...	Geo2D
EV_500_Aggr1km_RefSB_Uncert_I...	Earth View 500M Aggregated ...	Geo2D
EV_Band26	Earth View Band 26 Scaled Int...	Geo2D
EV_Band26_Uncert_Indexes	Earth View Band 26 Uncertain...	Geo2D
gflags	gflags	Geo2D
Height	Height	Geo2D
Range	Range	Geo2D
SensorAzimuth	SensorAzimuth	Geo2D
SensorZenith	SensorZenith	Geo2D
SolarAzimuth	SolarAzimuth	Geo2D
SolarZenith	SolarZenith	Geo2D
▼ Geolocation_Fields	HDFEOS/SWATHS/MODIS_SWA...	—
Latitude	latitude	Geo2D
Latitude_5x	Latitude	Geo2D
Longitude	longitude	Geo2D
Longitude_5x	Longitude	Geo2D

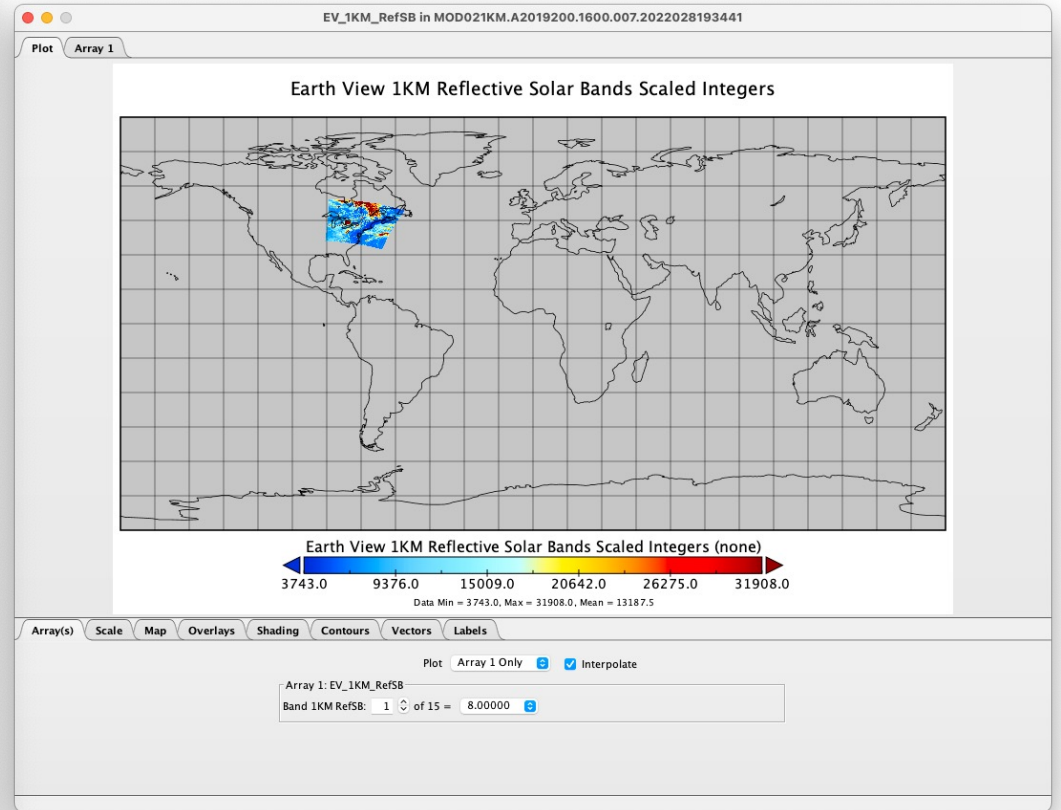
Show: All variables

Group "Geolocation_Fields"

In file
"MOD021KM.A2019200.1600.007.2022028193441.nc"

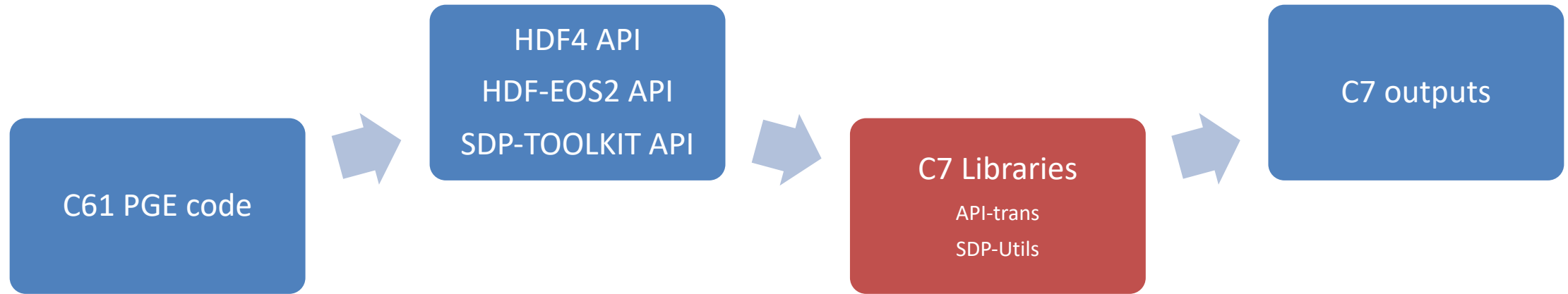
Group full name: HDFEOS/SWATHS/MODIS_SWATH_Type_L1B/

```
dimensions:  
  Band_250M = 2;  
  Band_500M = 5;  
  Band_1KM_RefSB = 15;  
  Band_1KM_Emissive = 16;  
  10*nscans = 2040;  
  Max_EV_frames = 1354;  
  2*nscans = 408;  
  1KM_geo_dim = 271;  
variables:  
  int 10*nscans(2*nscans=408);  
    :DimensionMap = "";  
  
  int Max_EV_frames(1KM_geo_dim=271);  
    :DimensionMap = "";  
  
group: Geolocation_Fields {  
  variables:  
    float Longitude_5x(10*nscans=2040, Max_EV_fr  
      :units = "degrees_east";  
      :long_name = "Longitude";  
      :standard_name = "longitude";  
      :description = "Added for CF-1.6 compliant  
  
    float Latitude(2*nscans=408, 1KM_geo_dim=271  
      :valid_range = -90.0f, 90.0f; // float  
      :FillValue = -999.0f; // float
```





How C7 libraries work



- C7 Libraries will “translate” HDF4 / HDF-EOS2 API function calls to HDF5 / HDF-EOS5;
- C7 Libraries will handle the new format of PCF and MCF;
- C61 PGE code need no change – except to include a “apiTrans.h” header in some C files.